

Cops, Robber and Medianwidth Parameters

Konstantinos Stavropoulos

GRASTA 2017

10.04.17

Crete

Tree Decompositions

A *tree decomposition* \mathcal{D} of a graph G is a pair (T, \mathcal{Z}) , where T is a *tree*, $\mathcal{Z} = (Z_t)_{t \in V(T)}$, is a family of subsets of $V(G)$ (called bags) such that

- (T1) for every edge $uv \in E(G)$ there exists $t \in V(T)$ with $u, v \in Z_t$,
- (T2) for every $v \in V(G)$, the set $Z^{-1}(v) := \{t \in V(T) \mid v \in Z_t\}$ is a non-empty *connected* subset (a subtree) of T .

Tree Decompositions

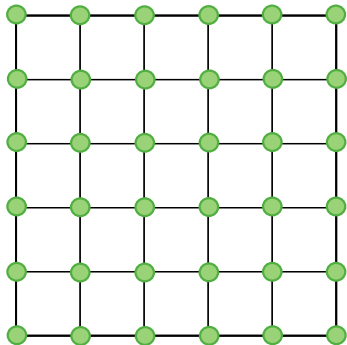
- ▶ The *width* of a tree decomposition $\mathcal{D} = (T, \mathcal{Z})$ is the number

$$\max\{|Z_t| - 1 \mid t \in V(T)\}.$$

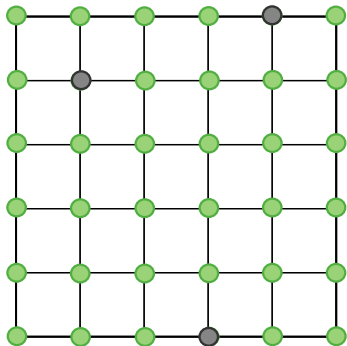
- ▶ Let \mathcal{T}^G be the set of all tree decompositions of G . The *treewidth* $\text{tw}(G)$ of G is

$$\text{tw}(G) := \min_{\mathcal{D} \in \mathcal{T}^G} \max\{|Z_t| - 1 \mid t \in V(T)\}.$$

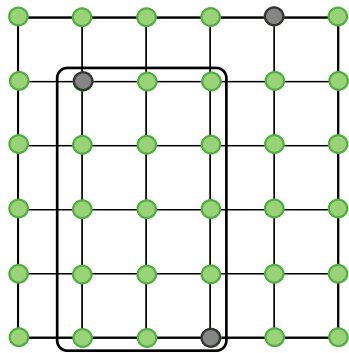
The Grid



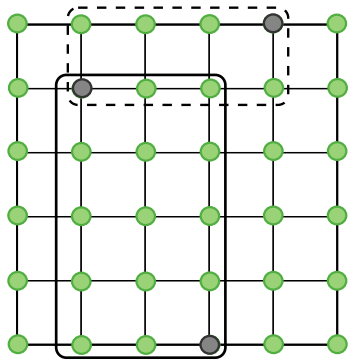
The Grid



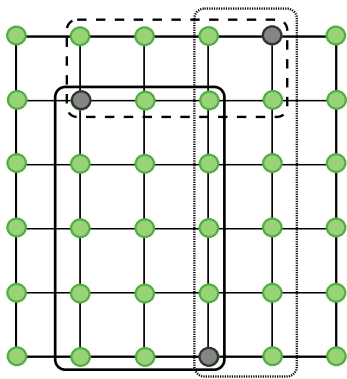
The Grid



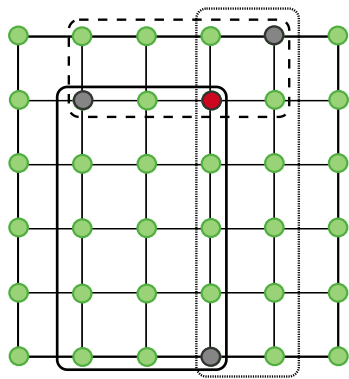
The Grid



The Grid



The Grid



Median Graphs

- ▶ *Interval* $I(u, v)$: all vertices on a shortest (u, v) -path (a (u, v) -geodesic):

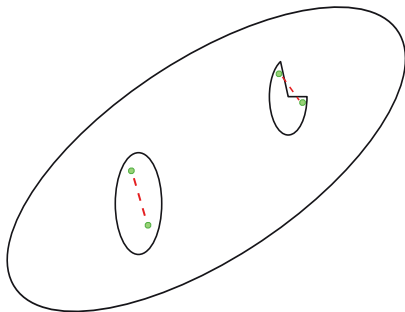
$$I(u, v) = \{x \in V(G) \mid d(u, v) = d(u, x) + d(x, v)\}.$$

- ▶ *Median Graph*: connected and for any vertices u, v, w there is a unique vertex x (the *median* of u, v, w) lying on a shortest (u, v) -path, a shortest (v, w) -path and a shortest (w, u) -path:

$$|I(u, v) \cap I(v, w) \cap I(w, u)| = 1$$

Convexity

A vertex set S is a *convex subset* of a graph if for every $u, v \in S$, $I(u, v) \subseteq S$.



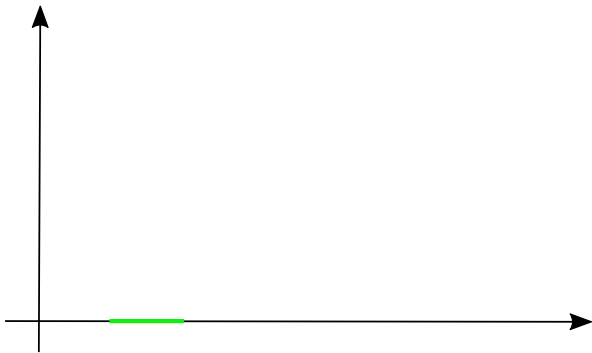
Not Enough Space



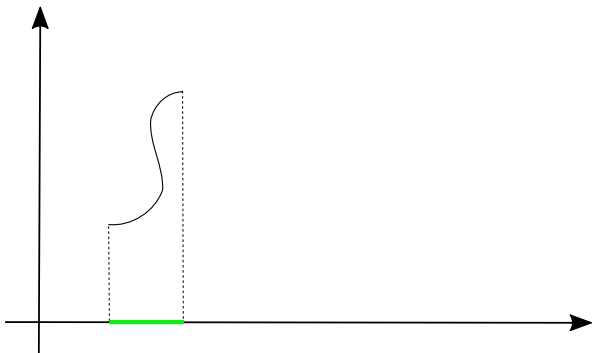
Not Enough Space



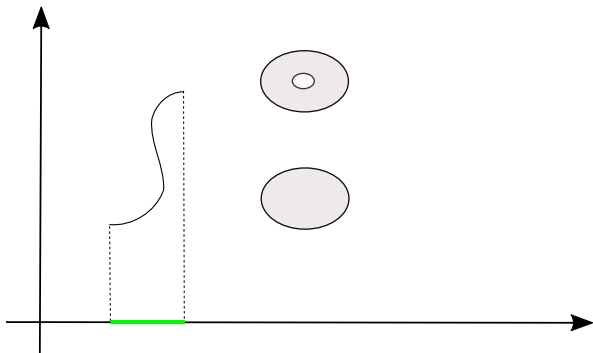
Not Enough Space



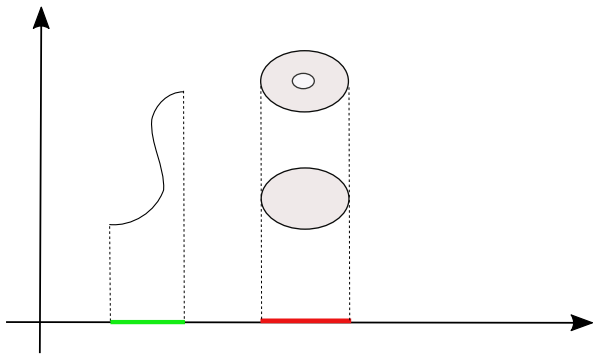
Not Enough Space



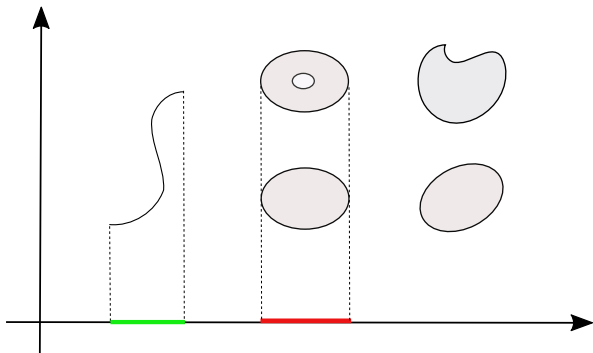
Not Enough Space



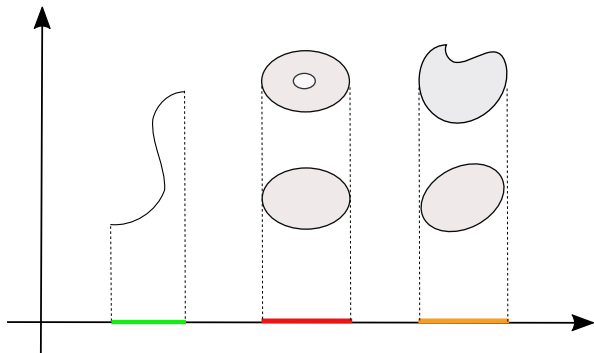
Not Enough Space



Not Enough Space



Not Enough Space



The Crucial Observation

Convexity degenerates to connectedness on trees!

Tree Decompositions

A *tree decomposition* \mathcal{D} of a graph G is a pair (T, \mathcal{Z}) , where T is a *tree*, $\mathcal{Z} = (Z_t)_{t \in V(T)}$, is a family of subsets of $V(G)$ (called bags) such that

- (T1) for every edge $uv \in E(G)$ there exists $t \in V(T)$ with $u, v \in Z_t$,
- (T2) for every $v \in V(G)$, the set $Z^{-1}(v) := \{t \in V(T) \mid v \in Z_t\}$ is a non-empty *connected* subset (a subtree) of T .

Median Decompositions

A *median decomposition* \mathcal{D} of a graph G is a pair (M, \mathcal{X}) , where M is a *median graph*, $\mathcal{X} = (X_a)_{a \in V(M)}$, is a family of subsets of $V(G)$ (called bags) such that

- (M1) for every edge $uv \in E(G)$ there exists $a \in V(M)$ with $u, v \in X_a$,
- (M2) for every $v \in V(G)$, the set $X^{-1}(v) := \{a \in V(M) \mid v \in X_a\}$ is a non-empty *convex* subset of M .

Median Decompositions

- ▶ The *width* of a median decomposition $\mathcal{D} = (T, \mathcal{X})$ is the number

$$\max\{|X_a| \mid a \in V(M)\}.$$

Median Decompositions

- ▶ The *width* of a median decomposition $\mathcal{D} = (T, \mathcal{X})$ is the number

$$\max\{|X_a| \mid a \in V(M)\}.$$

- ▶ Let \mathcal{M}^G be the set of all median decompositions of G . The *medianwidth* $\text{mw}(G)$ of G is

$$\text{mw}(G) := \min_{\mathcal{D} \in \mathcal{M}^G} \max\{|X_a| \mid a \in V(M)\}.$$

Median Decompositions

- ▶ The *width* of a median decomposition $\mathcal{D} = (T, \mathcal{X})$ is the number

$$\max\{|X_a| \mid a \in V(M)\}.$$

- ▶ Let \mathcal{M}^G be the set of all median decompositions of G . The *medianwidth* $\text{mw}(G)$ of G is

$$\text{mw}(G) := \min_{\mathcal{D} \in \mathcal{M}^G} \max\{|X_a| \mid a \in V(M)\}.$$

- ▶ By definition, $\text{mw}(G) \leq \text{tw}(G) + 1$.

The Clique Number

Theorem

For any graph G , $\text{mw}(G) = \omega(G)$.

Bounding the Dimension

- ▶ *tree dimension*: the minimum k such that G has an isometric embedding into a Cartesian product of k trees.
- ▶ *lattice dimension*: the minimum k such that G has an isometric embedding into a Cartesian product of k paths.
- ▶ Median graphs have finite lattice and tree dimension.

Bounding the Dimension

- ▶ An *i -median decomposition* of G is a median decomposition $\mathcal{D} = (M, \mathcal{X})$ satisfying (M1),(M2), where M has tree dimension at most i

Bounding the Dimension

- ▶ An *i -median decomposition* of G is a median decomposition $\mathcal{D} = (M, \mathcal{X})$ satisfying (M1),(M2), where M has tree dimension at most i
- ▶ \mathcal{M}_i^G : the set of i -median decompositions of G
- ▶ The *i -medianwidth* $\text{mw}_i(G)$ of G is

$$\text{mw}_i(G) := \min_{\mathcal{D} \in \mathcal{M}_i^G} \max\{|X_a| \mid a \in V(M)\}.$$

Bounding the Dimension

- ▶ An *i -lattice decomposition* of G is a median decomposition $\mathcal{D} = (M, \mathcal{X})$ satisfying (M1),(M2), where M has lattice dimension at most i

Bounding the Dimension

- ▶ An *i -lattice decomposition* of G is a median decomposition $\mathcal{D} = (M, \mathcal{X})$ satisfying (M1),(M2), where M has lattice dimension at most i
- ▶ \mathcal{L}_i^G : the set of i -lattice decompositions of G
- ▶ The *i -latticewidth* $\text{lw}_i(G)$ of G is

$$\text{lw}_i(G) := \min_{\mathcal{D} \in \mathcal{L}_i^G} \max\{|X_a| \mid a \in V(M)\}.$$

Bounding the Dimension

► $\text{mw}_1(G) = \text{tw}(G) + 1, \text{lw}_1(G) = \text{pw}(G) + 1$

Bounding the Dimension

▶ $\text{mw}_1(G) = \text{tw}(G) + 1, \text{lw}_1(G) = \text{pw}(G) + 1$

- ▶ the invariants mw_i, lw_i form non-increasing sequences:

$$\text{tw}(G) + 1 = \text{mw}_1(G) \geq \text{mw}_2(G) \geq \cdots \geq \text{mw}_\infty(G) = \omega(G).$$

$$\text{pw}(G) + 1 = \text{lw}_1(G) \geq \text{lw}_2(G) \geq \cdots \geq \text{lw}_\infty(G) = \omega(G).$$

i -Medianwidth

Theorem

For any graph G and any integer $i \geq 1$,

$$\text{mw}_i(G) = \min_{\mathcal{D}^1, \dots, \mathcal{D}^i \in \mathcal{T}^G} \max\left\{ \left| \bigcap_{j=1}^i Z_{t_j}^j \right| \mid t_j \in V(T^j) \right\}.$$

i -Medianwidth

Theorem

For any graph G and any integer $i \geq 1$,

$$\text{mw}_i(G) = \min_{\mathcal{D}^1, \dots, \mathcal{D}^i \in \mathcal{T}G} \max\left\{ \left| \bigcap_{j=1}^i Z_{t_j}^j \right| \mid t_j \in V(T^j) \right\}.$$

i -Medianwidth

Theorem

For any graph G and any integer $i \geq 1$,

$$\text{mw}_i(G) = \min_{\mathcal{D}^1, \dots, \mathcal{D}^i \in \mathcal{T}G} \max\left\{ \left| \bigcap_{j=1}^i Z_{t_j}^j \right| \mid t_j \in V(T^j) \right\}.$$

i -Medianwidth

Theorem

For any graph G and any integer $i \geq 1$,

$$\text{mw}_i(G) = \min_{D^1, \dots, D^i \in \mathcal{T}G} \max\left\{ \left| \bigcap_{j=1}^i Z_{t_j}^j \right| \mid t_j \in V(T^j) \right\}.$$

i -Medianwidth

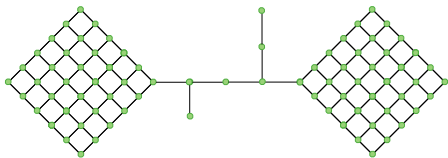
Theorem

For any graph G and any integer $i \geq 1$,

$$\text{mw}_i(G) = \min_{\mathcal{D}^1, \dots, \mathcal{D}^i \in \mathcal{T}^G} \max \left\{ \left| \bigcap_{j=1}^i Z_{t_j}^j \right| \mid t_j \in V(T^j) \right\}.$$

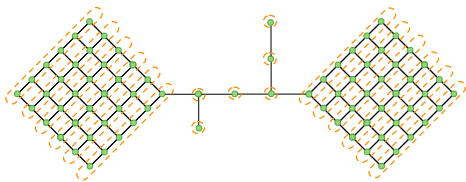
i -Medianwidth

Intuition



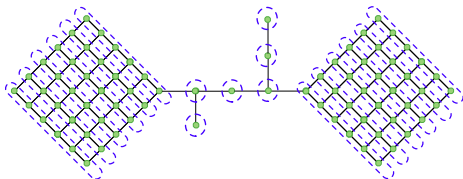
i -Medianwidth

Intuition



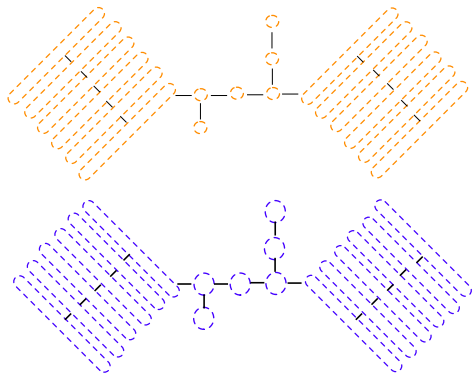
i -Medianwidth

Intuition



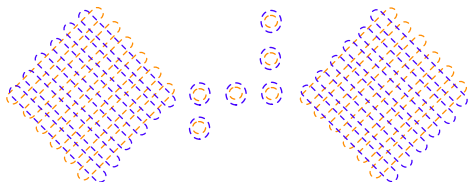
i -Medianwidth

Intuition



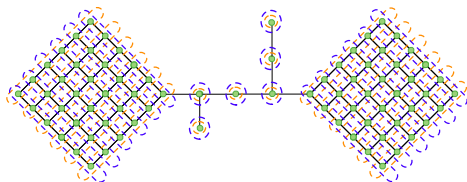
i -Medianwidth

Intuition



i -Medianwidth

Proof Intuition



A Game Characterisation

Cops and Robber

- ▶ A team of k Cops try to capture a Robber on a graph G , robber wants to escape for ever.
- ▶ In each round: some cops move with a helicopter from one vertex to another
- ▶ while the cops are in the air, the Robber can arbitrarily fast move to any vertex through a path in the graph...
- ▶ ...as long as there is no Cop on the ground standing on a vertex in the path.

A Game Characterisation

Two variations

- ▶ (Seymour and Thomas) A team of k Cops can always capture a *visible* Robber on a graph G if and only if $\text{tw}(G) \leq k - 1$.
- ▶ (Lapaugh, Kirousis and Papadimitriou, Bienstock et al) A team of k Cops can always capture an *invisible* Robber on a graph G if and only if $\text{pw}(G) \leq k - 1$.

A Game Characterisation

i-Cops and Robber

- ▶ i different teams of $|V(G)|$ cops each try to capture a Robber simultaneously on a graph G .
- ▶ cop teams "invisible" to each other
- ▶ need to cooperate in order to capture the robber with the least "cooperation" possible
- ▶ robber is powerful: she can be fully caught only if every team captures her at the same time.
- ▶ she chooses which team of cops can move in each round

A Game Characterisation

i-Cops and Robber

- ▶ cops: when a team of cops is chosen, they play as in the classical game
- ▶ cops also have some power; robber still can't travel through them
- ▶ if a team captures the Robber, then it locks down and can't be chosen to move again for the rest of the game; the robber from then on can only move to vertices occupied by the team.
- ▶ cop *cooperation*: the maximum number of vertices simultaneously occupied by a cop of every team at any point of the game.

A Game Characterisation

Two variations

- ▶ i cop teams can *monotonely* capture a *visible* robber on a graph G with cooperation at most k if and only if $\text{mw}_i(G) \leq k$.
- ▶ i cop teams can *monotonely* capture an *invisible* robber on a graph G with cooperation at most k if and only if $\text{lw}_i(G) \leq k$.

Non-monotonicity in i-Cops and Robber game

- ▶ For treewidth, monotone and non-monotone strategies are equally strong.

Non-monotonicity in i-Cops and Robber game

- ▶ For treewidth, monotone and non-monotone strategies are equally strong.
- ▶ What is the case for i-medianwidth?

Cops, Robber and Medianwidth Parameters

Thank you for your attention!